

# A generalized random forest framework for improved prediction and interpretations

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# Why Random Forests?

- + A **powerful, nonparametric prediction algorithm**, which often outperforms deep learning on moderate-sized tabular datasets

“ ... the method that performs consistently well across all dimensions is **random forests**, ” followed by neural nets, boosted trees, and SVMs. [11 datasets]

- Caruana, Karampatziakis, Yessenalina (2008)

“ The classifiers most likely to be the bests are the **random forest** versions. ” [121 data sets, 179 models]

- Fernandez-Delgado, Cernadas, Barro, Amorim (2014)

“ *Why do tree-based models still outperform deep learning on tabular data?* ... tree-based models [i.e., **random forests**, XGBoost] remain state-of-the-art on medium-sized data (~10K samples) even without accounting for their superior speed. [45 data sets]

- Grinsztajn, Oyallon, Varoquaux (2022)

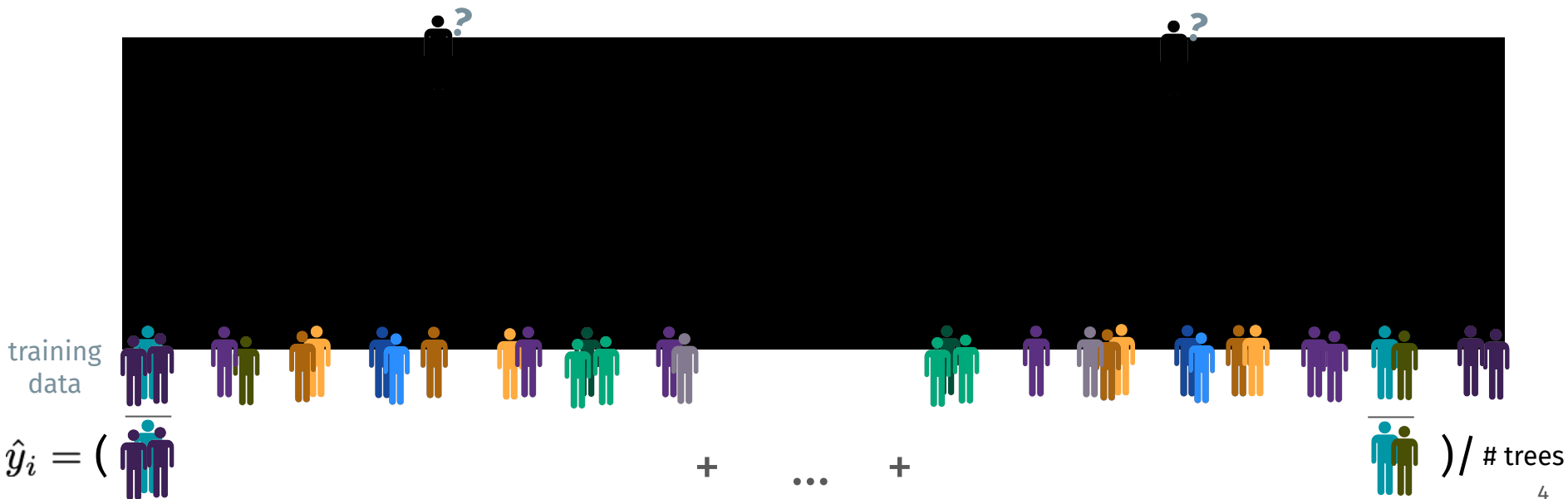
# Why Random Forests?

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- + A **powerful, nonparametric prediction algorithm**, which often outperforms deep learning on moderate-sized tabular datasets
- + Numerous feature importance measures exist to enable **interpretability**  
[Breiman 2001, Ishwaran 2007, Epifanio 2017, Kazemitabar et al. 2017, Li et al. 2019, Lundberg et al. 2020, Klusowski and Tian 2021, Saabas 2022, and more...]
  - o **Mean Decrease in Impurity (MDI)**: most popular in practice (and default feature importance in sklearn) [Breiman et al. 1984]

# Random Forest (RF) [Breiman 2001]

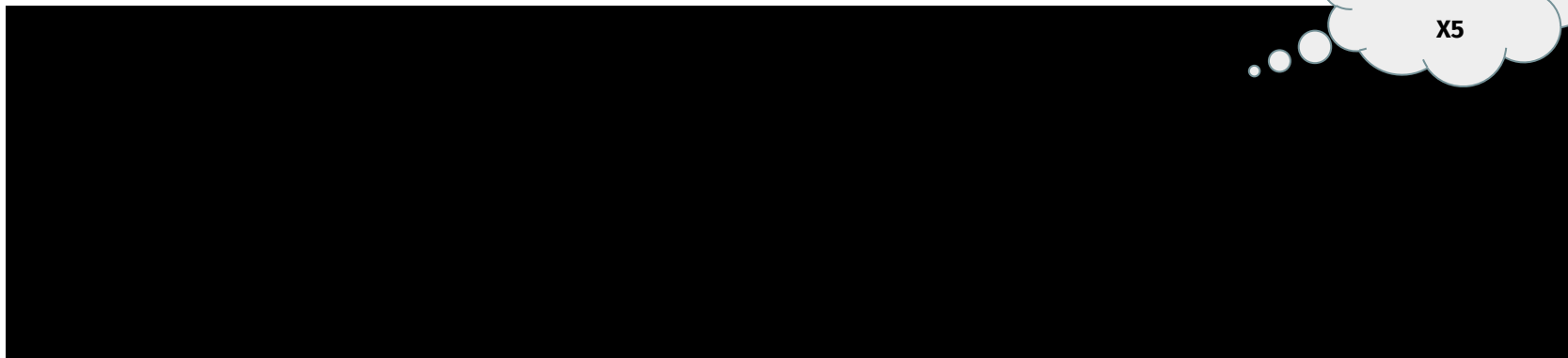
A **collection of decision trees**, where



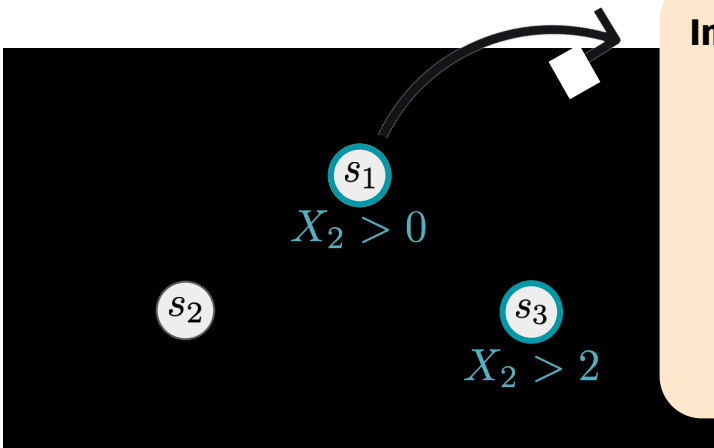
# Random Forest (RF) [Breiman 2001]

A **collection of decision trees**, where

- each tree is fitted on a different **bootstrap** version of the data
- **features are subsampled** at each node



# Mean Decrease in Impurity (MDI)



## Impurity decrease at $s_1$

“Measures decrease in variance from making the split”

$$\hat{\Delta}(s_1) = \underbrace{\sum_{\mathbf{x} \in s_1} (y_i - \bar{y}_{s_1})^2}_{\text{Var}(\text{node of interest})} - \underbrace{\sum_{\mathbf{x} \in s_2} (y_i - \bar{y}_{s_2})^2}_{\text{Var}(\text{left child node})} - \underbrace{\sum_{\mathbf{x} \in s_3} (y_i - \bar{y}_{s_3})^2}_{\text{Var}(\text{right child node})}$$

For each feature  $k$ ,  $MDI(k)$  is the weighted sum of impurity decreases across nodes that split on  $X_k$ , e.g.,

$$MDI(X_2) = \frac{n_1}{n} \hat{\Delta}(s_1) + \frac{n_3}{n} \hat{\Delta}(s_3)$$

# Mean Decrease in Impurity (MDI)

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## Advantages of MDI:

Conceptually simple

Fast to compute

## Well-known drawbacks of MDI:

Unstable in **low-signal** problems

Biased against features are highly **correlated** or have low **entropy**

Inefficient measure if **additive structure** is present **(Limitation of RF)**

Nicodemus, K. K. and Malley, J. D. "Predictor correlation impacts machine learning algorithms: implications for genomic studies." *Bioinformatics* (2009)

Nicodemus, K. K. "On the stability and ranking of predictors from random forest variable importance measures." *Briefings in Bioinformatics* (2011)

Tan, Y. S., Agarwal, A., and Yu, B. "A cautionary tale on fitting decision trees to data from additive models: generalization lower bounds." *AISTATS* (2022)

# Talk outline

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- 0 We exploit a recent connection between **decision trees** and **linear regression**
- 1 We develop **RF+**, a generalization of RFs, which improves upon the **prediction** accuracy of RFs, especially when there is smooth additive structure
  - + Extensions of RF+, including to the network (or spatial) data setting
- 2 We develop **MDI+**, a generalization of MDI, which provides a general framework for improved **interpretations** using RF/RF+

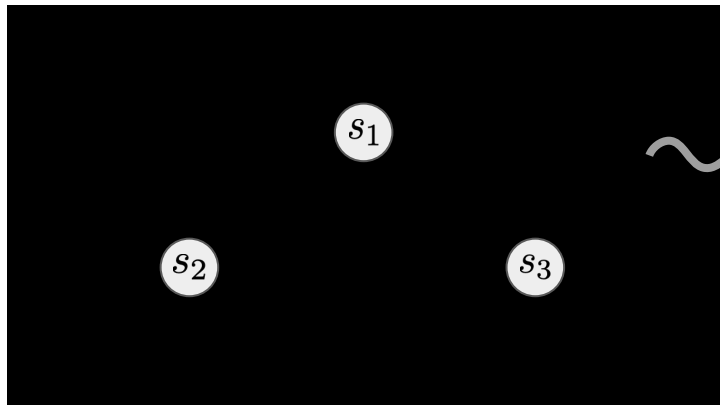


# Reinterpreting decision trees via linear regression

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# Connecting decision trees to linear regression

Step 1: Obtain engineered “stump” features  $\psi(\cdot; s_k)$  from decision tree



$$\psi(\mathbf{x}; s_k) = \begin{cases} 0 & \text{if } \mathbf{x} \notin s_k \\ \frac{-N_R}{\sqrt{N_L N_R}} & \text{if } \mathbf{x} \in \text{left child of } s_k \\ \frac{N_L}{\sqrt{N_L N_R}} & \text{if } \mathbf{x} \in \text{right child of } s_k \end{cases}$$

node  $\uparrow$   
Input data  $\mathbf{x} \in \mathbb{R}^p$   $\downarrow$

where  $N_R$  = number of samples in right child of  $s_k$

$N_L$  = number of samples in left child of  $s_k$



$$\Psi(\mathbf{X}; \mathcal{S}) := \begin{array}{c} \text{Orange person} \\ \text{Blue person} \\ \vdots \end{array} \begin{array}{ccc} s_1 & s_2 & s_3 \\ \hline - & + & 0 \\ + & 0 & - \\ \vdots & \vdots & \vdots \end{array}$$

**A new basis using supervised tree features**

# Connecting decision trees to linear regression

Step 2: Fit OLS on stump features

$$\mathbf{y} \sim \Psi(\mathbf{X}, \mathcal{S})$$

**Key Connection: OLS predictions = original tree predictions** [Klusowski 2021]

↘ assuming tree prediction = mean response per leaf node  
(e.g., in CART)

**Upshot #1:** Provides a natural framework for developing a new class of prediction models → RF+

**Upshot #2:** Reinterpret MDI via linear regression → MDI+

**RF+:**

**A generalization of random forests**

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# RF+: A generalization of random forests

A decision tree  
in **RF**:

$$\arg \min_{\tau \in \mathbb{R}^{\# \text{ stumps}}} \|\mathbf{y} - \Psi(\mathbf{X})\tau\|_2^2$$

A decision tree  
in **RF+**:

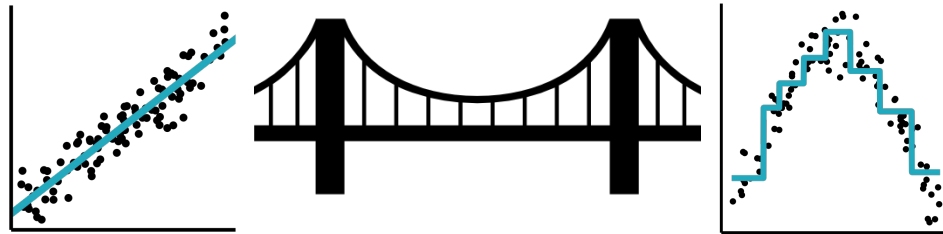
$$\arg \min_{\substack{\beta \in \mathbb{R}^p \\ \tau \in \mathbb{R}^{\# \text{ stumps}}} \|\mathbf{y} - \underbrace{\mathbf{X}\beta}_{\text{Linear}} - \underbrace{\Psi(\mathbf{X})\tau}_{\text{Nonlinear}}\|_2^2 + P_\beta(\beta) + P_\tau(\tau)$$

- + Why restrict ourselves to only stump features?  
This is the source of RF's implicit bias against smooth data structures
- + Why not add regularization?
- + Why restrict ourselves to  $L_2$  loss?

# RF+: A generalization of random forests

**RF+:** a new class of prediction algorithms, which generalizes RFs

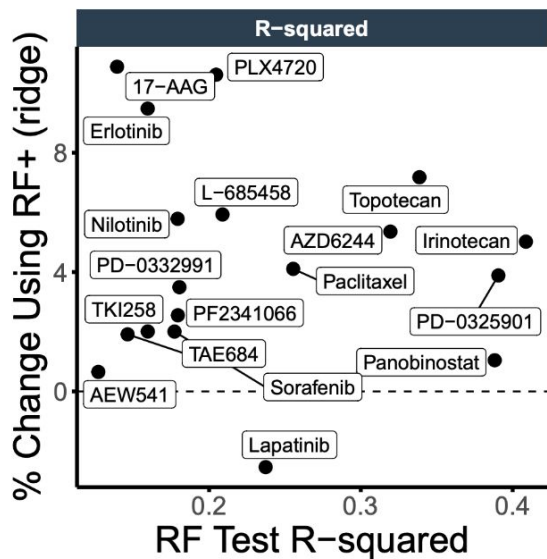
$$\arg \min_{\substack{\beta \in \mathbb{R}^p \\ \tau \in \mathbb{R}^{\# \text{ stumps}}} \| \mathbf{y} - \underbrace{\mathbf{X}\beta}_{\text{Linear}} - \underbrace{\Psi(\mathbf{X})\tau}_{\text{Nonlinear}} \|_2^2 + P_\beta(\beta) + P_\tau(\tau)$$



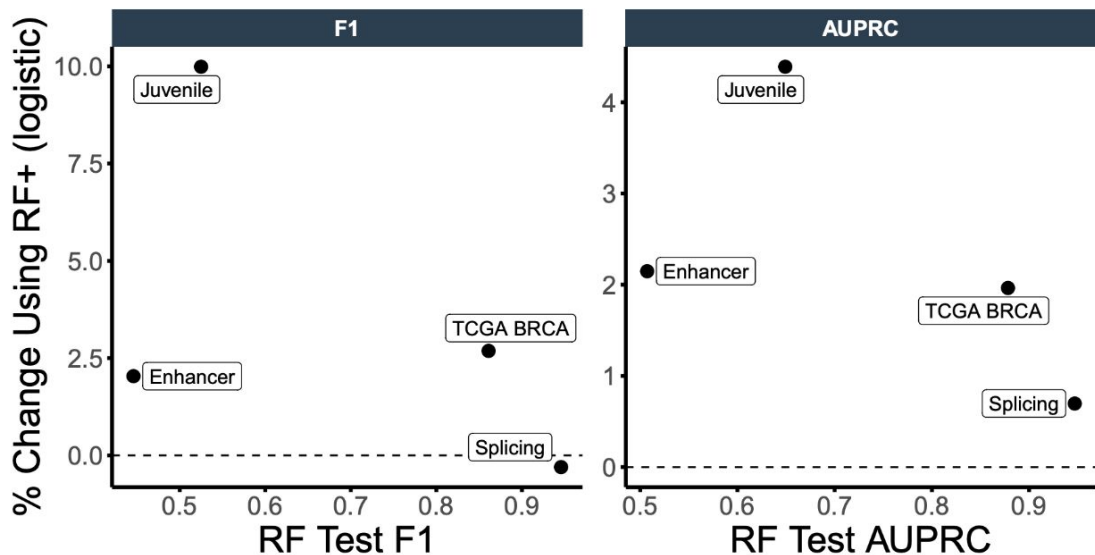
- + Fitted per tree using bootstrapped samples and averaged across trees
- + Ridge penalty generally works well
- + Can apply general loss functions  
(e.g., logistic for classification, robust regression when outliers are present)

# RF+ improves **prediction accuracy** over RF

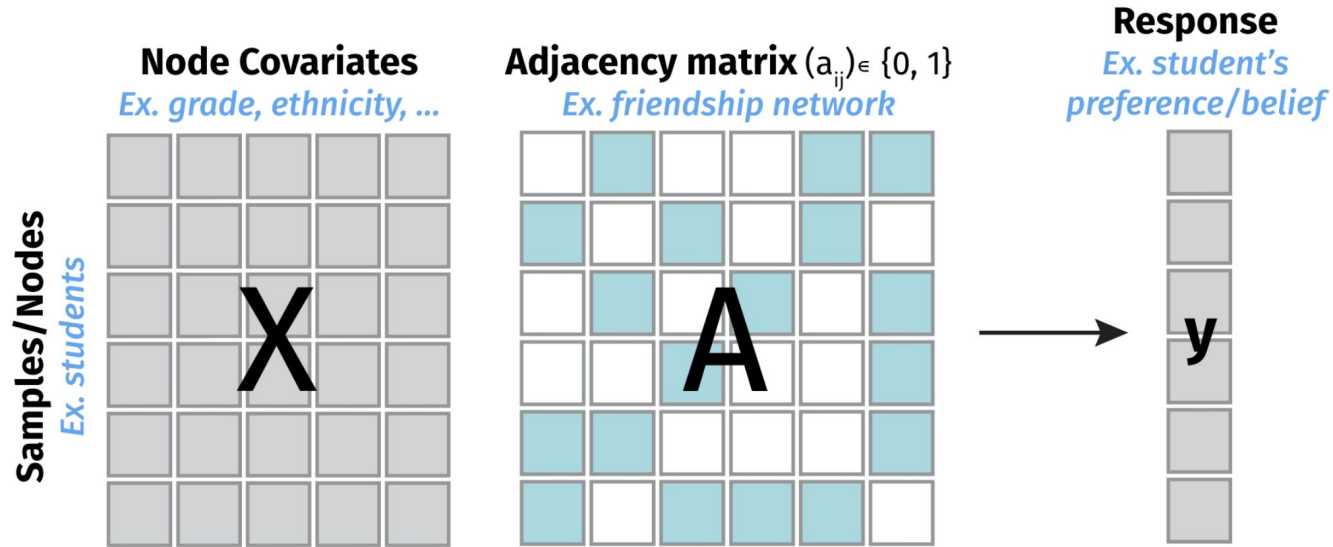
(A) Regression



(B) Classification



# Extending RF+ to network-assisted regression setting



**Network cohesion assumption:**  
neighboring nodes have similar responses to each other

(unnormalized) Laplacian  
 $L = D - A$  where  $D$  = degree matrix



# NeRF+: Network-assisted RF+

In the linear regression setting, network effects can be incorporated through a **network cohesion penalty** [Li et al. (2019)]:

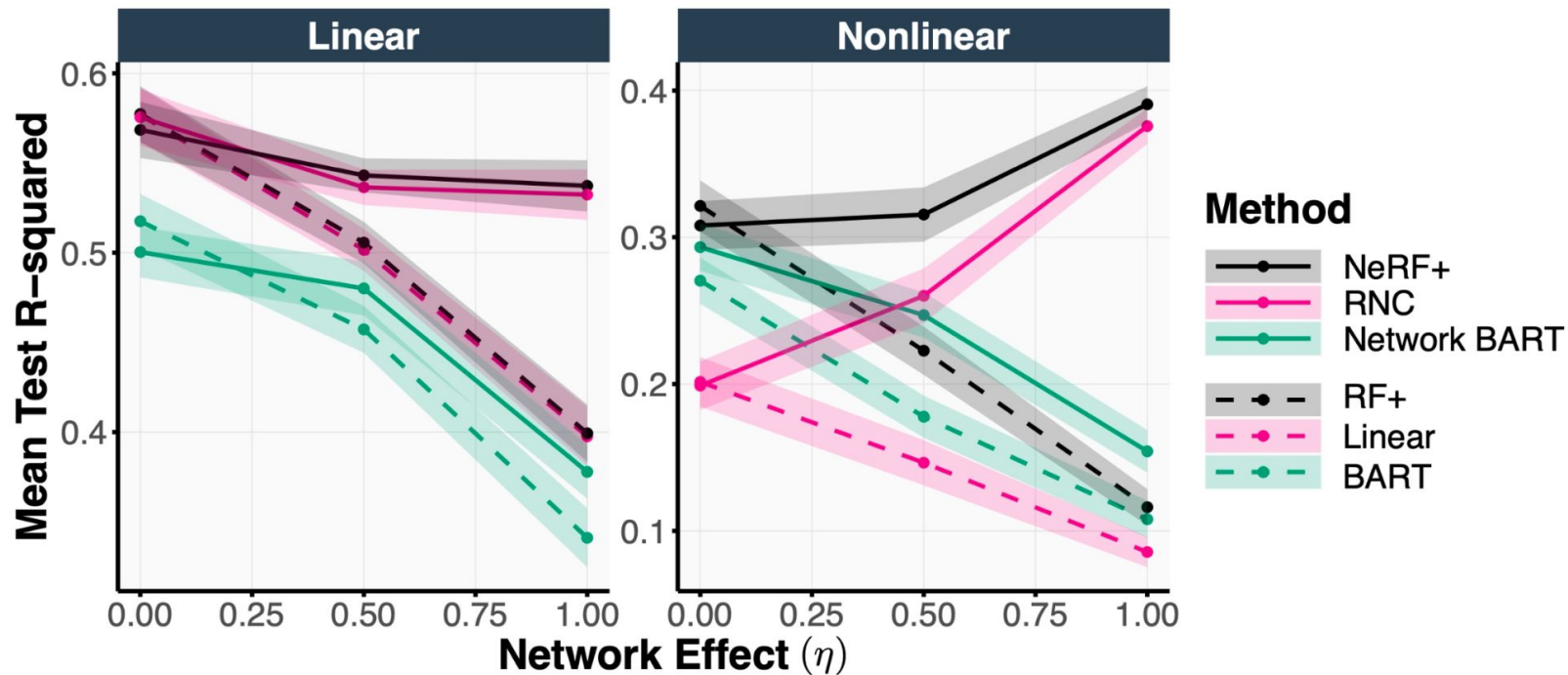
$$\arg \min_{\alpha \in \mathbb{R}^n, \beta \in \mathbb{R}^p} \underbrace{\|\mathbf{y} - \alpha - \mathbf{X}\beta\|_2^2}_{\text{Network Effects}} + \underbrace{\lambda \alpha^\top L \alpha}_{\text{Network Cohesion Penalty}}$$

where  $\alpha^\top L \alpha = \sum_{(i,j) \in E} (\alpha_i - \alpha_j)^2 = \sum_{i,j} A_{ij} (\alpha_i - \alpha_j)^2$

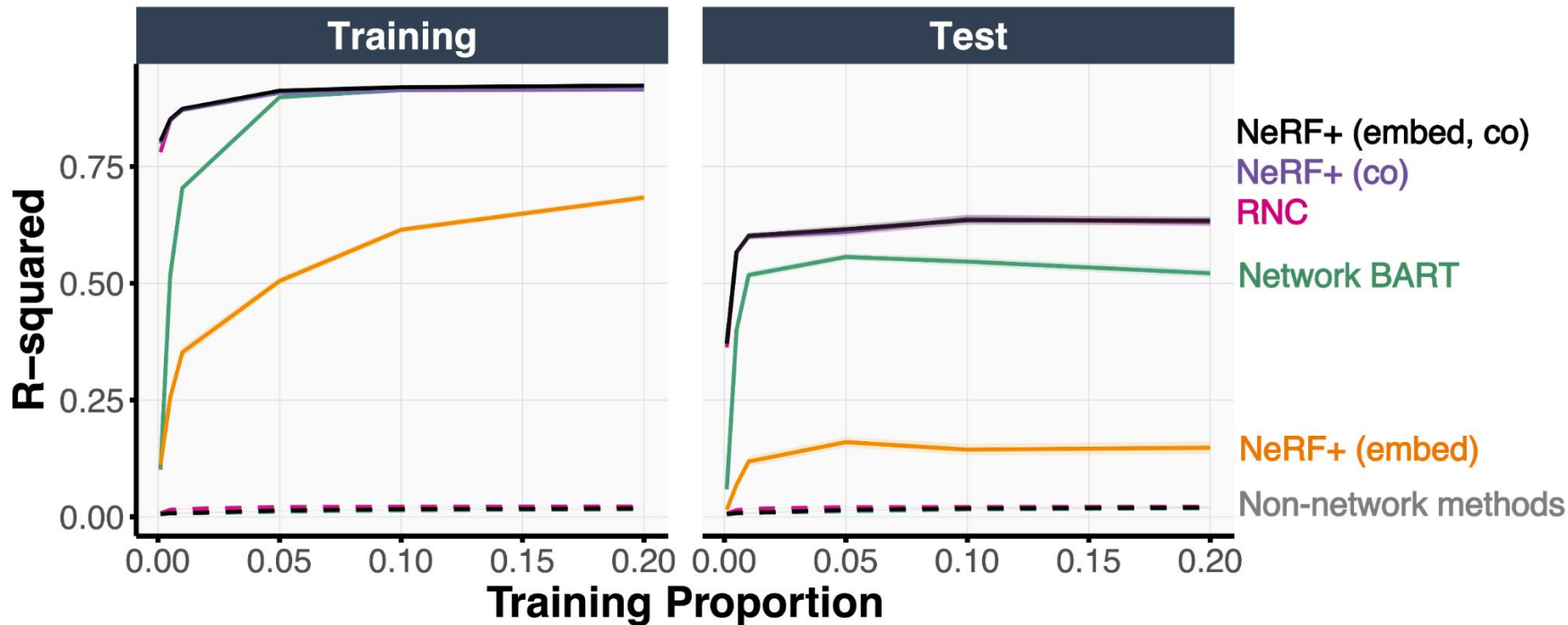
**NeRF+**: an extension of RF+ to exploit cohesion between samples in a network

$$\arg \min_{\substack{\alpha \in \mathbb{R}^n \\ \beta \in \mathbb{R}^p \\ \tau \in \mathbb{R}^{\# \text{ stumps}}} \underbrace{\|\mathbf{y} - \alpha - \mathbf{X}\beta - \underbrace{\Psi(\mathbf{X})\tau}_{\text{Nonlinear}}\|_2^2}_{\text{Network Effects}} + P_\beta(\beta) + P_\tau(\tau) + \underbrace{\lambda \alpha^\top L \alpha}_{\text{Network Cohesion Penalty}}$$

# NeRF+ improves prediction performance



# NeRF+ improves prediction on Philadelphia crime dataset



**MDI+:**

**A generalization of mean decrease in impurity**

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# Overview of MDI+

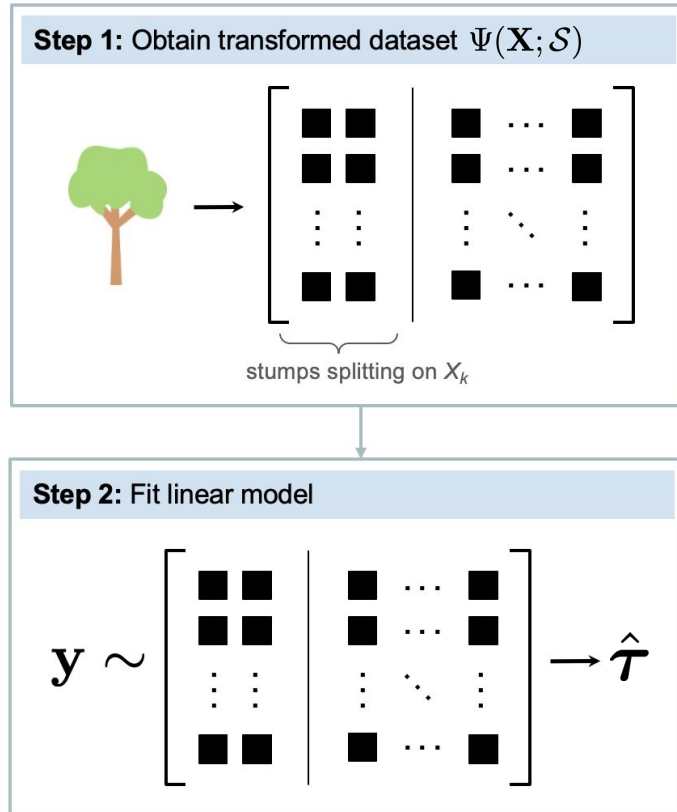
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## MDI+: a flexible framework for computing feature importances using RF/RF+

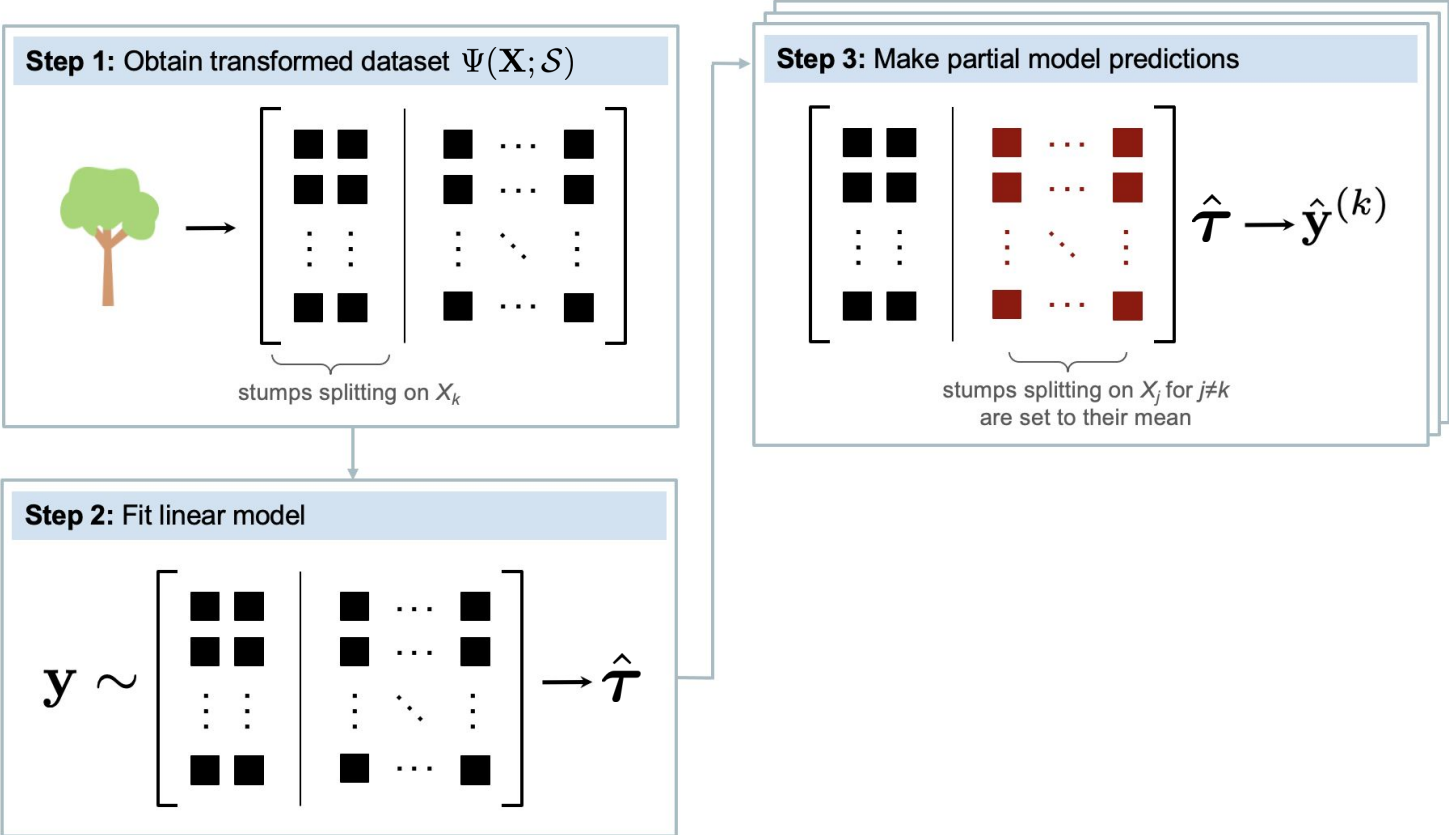
- + Avoids aforementioned drawbacks of MDI
- + Allows the analyst to tailor the feature importance computation to the data/problem structure (e.g., handle outliers, classification vs. regression)

**Key idea:** MDI can be viewed as an  $R^2$  value from a linear regression model

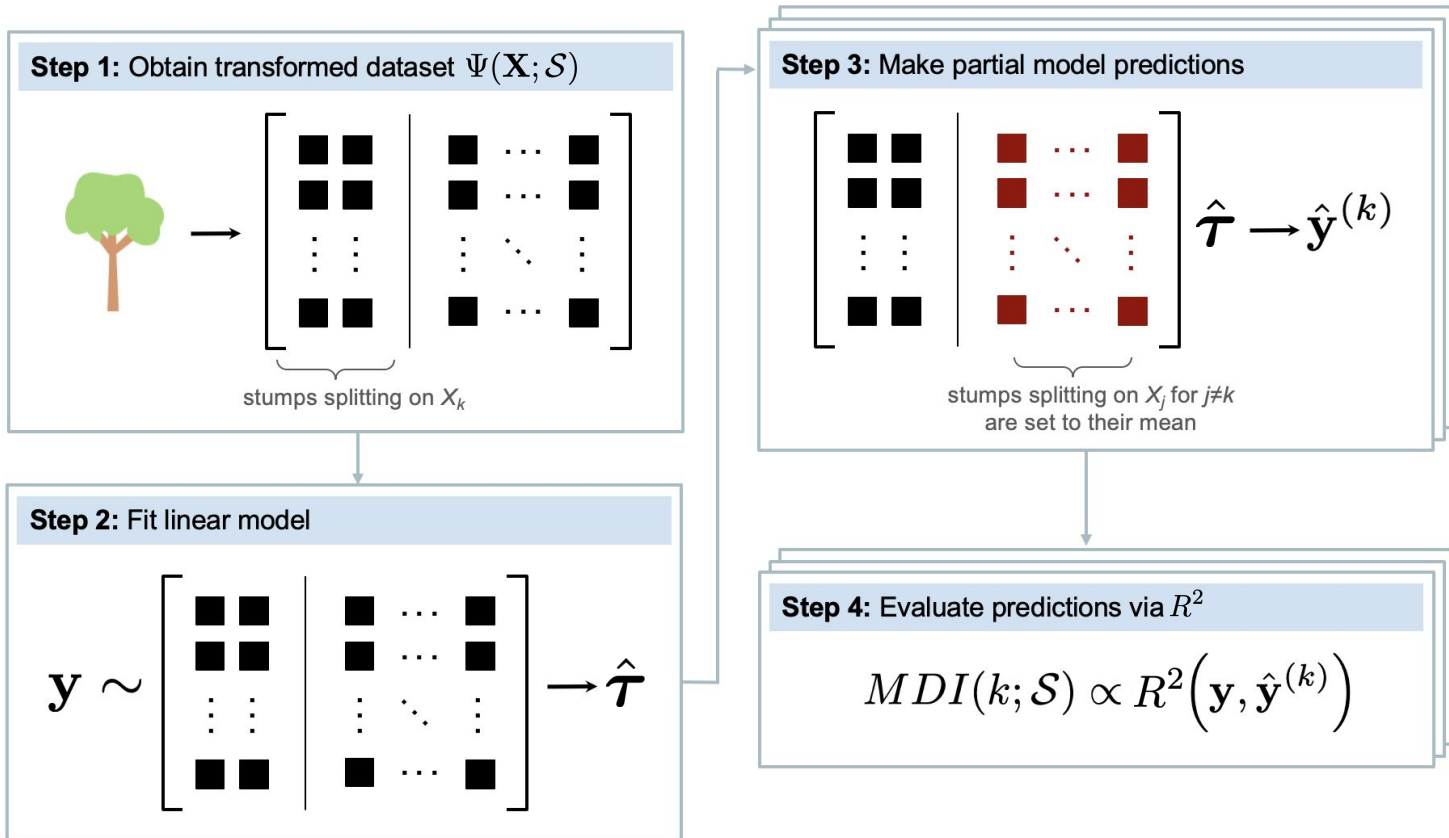
# Reinterpreting MDI as an $R^2$



# Reinterpreting MDI as an $R^2$

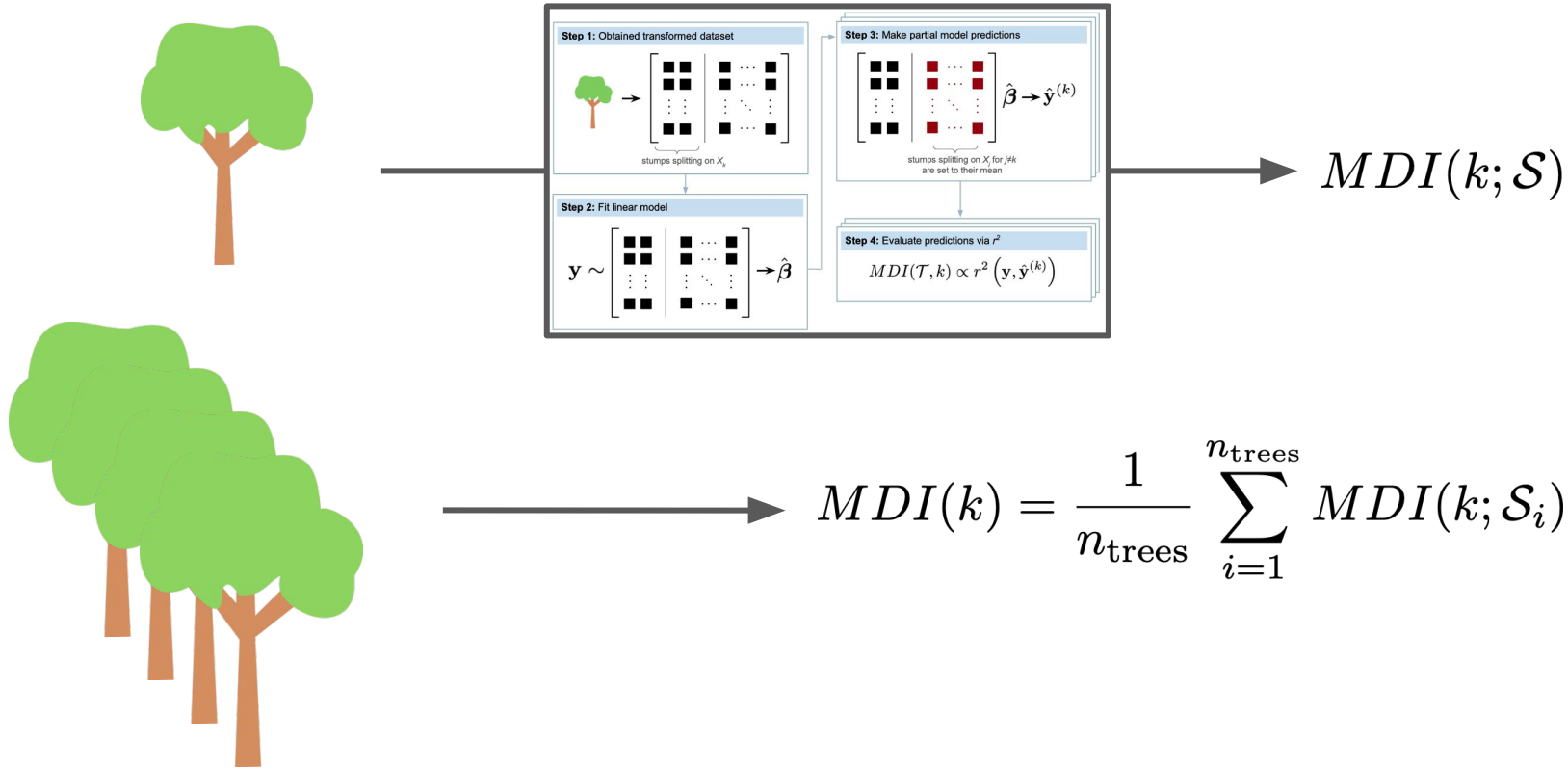


# Reinterpreting MDI as an $R^2$

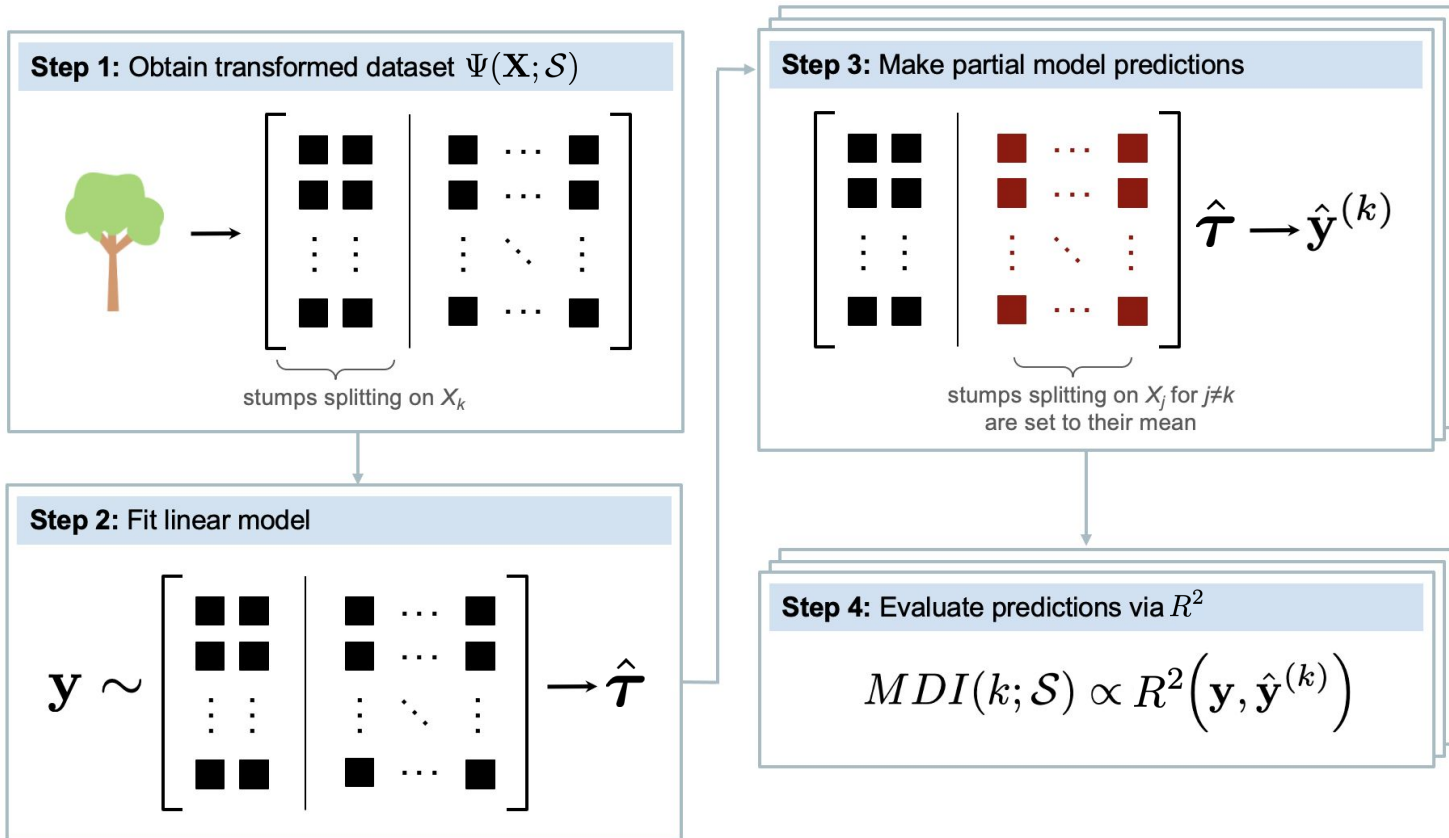




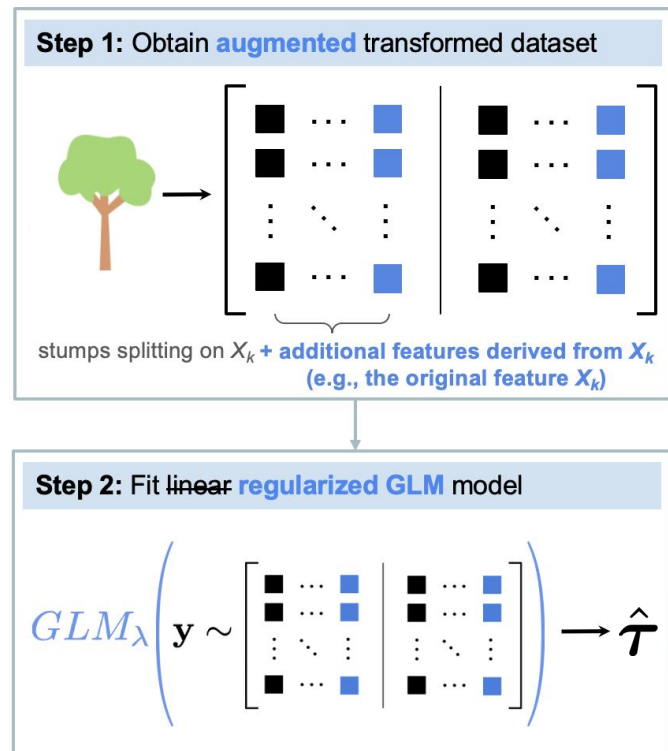
# Reinterpreting MDI as an $R^2$



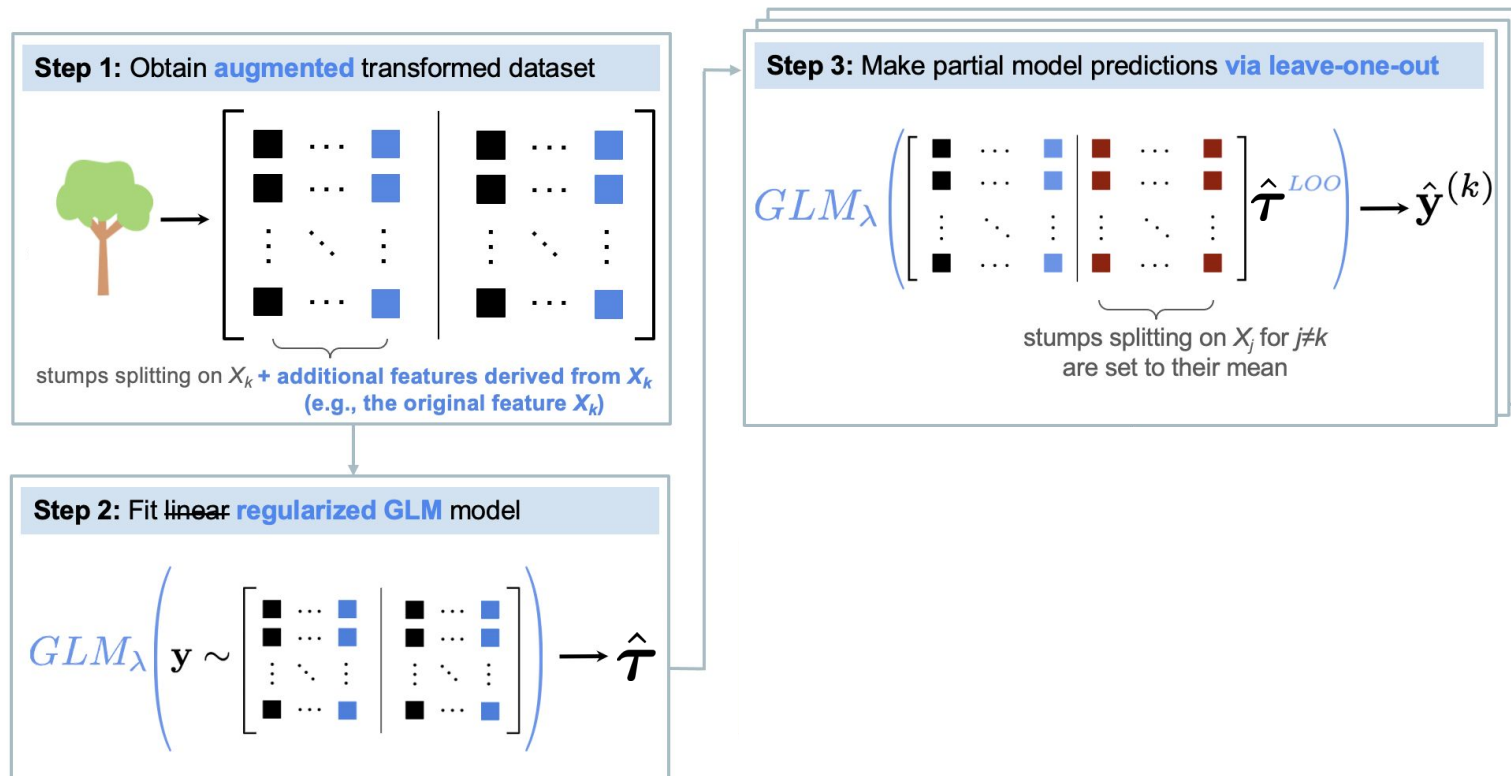
# Reinterpreting MDI as an $R^2$



# MDI+: A Generalized Mean Decrease in Impurity

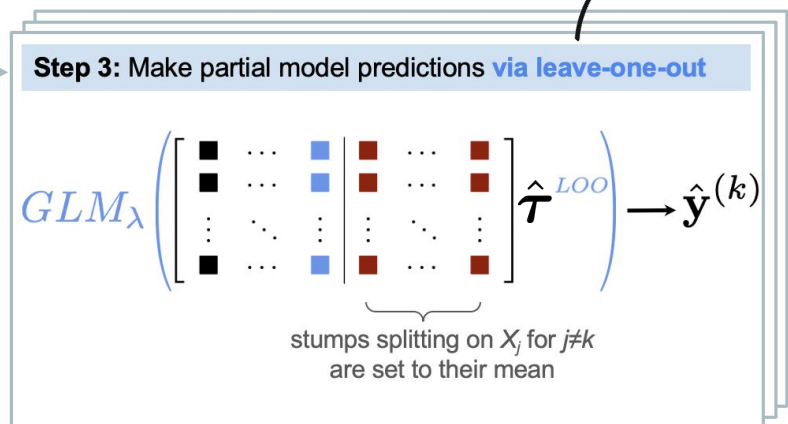
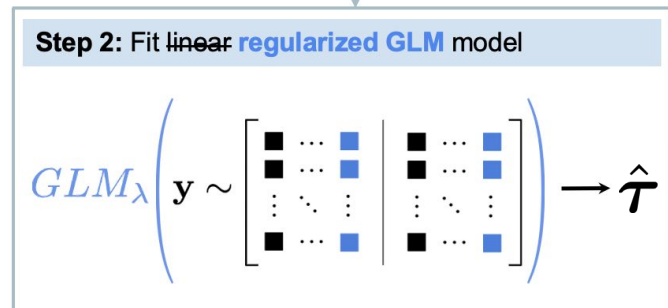
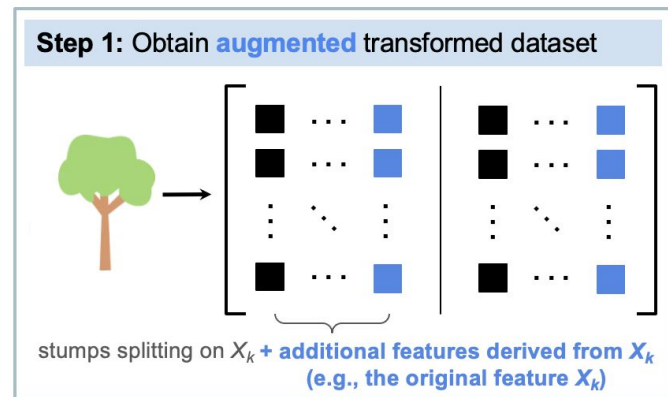


# MDI+: A Generalized Mean Decrease in Impurity



# MDI+: A Generalized Mean Decrease in Impurity

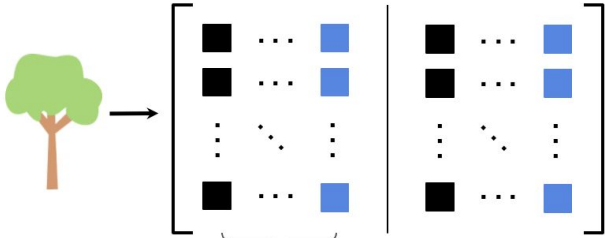
Approximate leave-one-out predictions can be computed without refitting the RF



# MDI+: A Generalized Mean Decrease in Impurity

Approximate leave-one-out predictions can be computed without refitting the RF

**Step 1: Obtain augmented transformed dataset**



stumps splitting on  $X_k$  + additional features derived from  $X_k$  (e.g., the original feature  $X_k$ )

**Step 2: Fit linear regularized GLM model**

$$GLM_\lambda \left( y \sim \left[ \begin{array}{c|c} \blacksquare \dots \blacksquare & \blacksquare \dots \blacksquare \\ \blacksquare \dots \blacksquare & \blacksquare \dots \blacksquare \\ \vdots & \vdots \\ \blacksquare \dots \blacksquare & \blacksquare \dots \blacksquare \end{array} \right] \right) \rightarrow \hat{\mathcal{T}}$$

**Step 3: Make partial model predictions via leave-one-out**

$$GLM_\lambda \left( \left[ \begin{array}{c|c} \blacksquare \dots \blacksquare & \blacksquare \dots \blacksquare \\ \blacksquare \dots \blacksquare & \blacksquare \dots \blacksquare \\ \vdots & \vdots \\ \blacksquare \dots \blacksquare & \blacksquare \dots \blacksquare \end{array} \right] \hat{\mathcal{T}}^{LOO} \right) \rightarrow \hat{y}^{(k)}$$

stumps splitting on  $X_j$  for  $j \neq k$  are set to their mean

**Step 4: Evaluate predictions via  $r^2$  metric of choice**

$$MDI^+(k; \mathcal{S}) = metric \left( y, \hat{y}^{(k)} \right)$$

# Roadmap of Empirical Results

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- + **Correlation/entropy bias:** MDI+ overcomes correlation and entropy bias using out-of-sample prediction
- + **Real data-inspired simulations:** MDI+ improves feature rankings in various regression, classification, and robust regression scenarios
  - Regression: MDI+ with ridge regression as GLM +  $r^2$  metric
  - Classification: MDI+ with  $l_2$ -regularized logistic regression as GLM + log-loss metric
  - Robust regression: MDI+ with regularized Huber regression as GLM + Huber loss metric
- + **Two real data case studies:** MDI+ identifies well-known gene predictors with greater stability than competing methods (for drug response prediction and breast cancer subtyping)

# Roadmap of Empirical Results

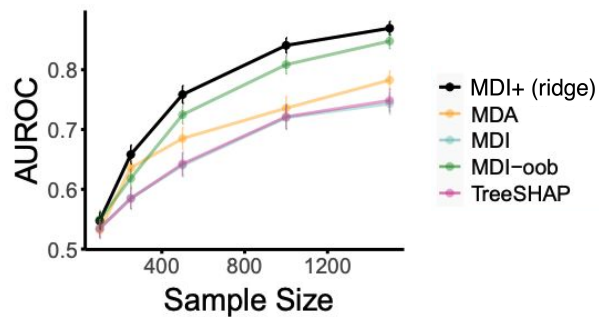
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- + **Real data-inspired simulations:** MDI+ improves feature rankings in various regression, classification, and robust regression scenarios
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- + **Two real data case studies:** MDI+ identifies well-known gene predictors with greater stability than competing methods (for drug response prediction and breast cancer subtyping)



# Regression simulation results

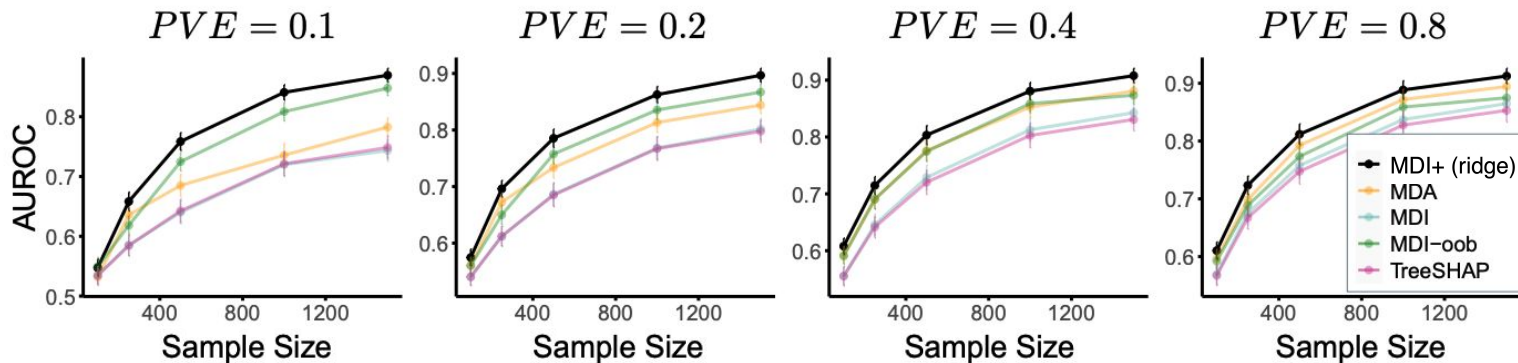
Linear



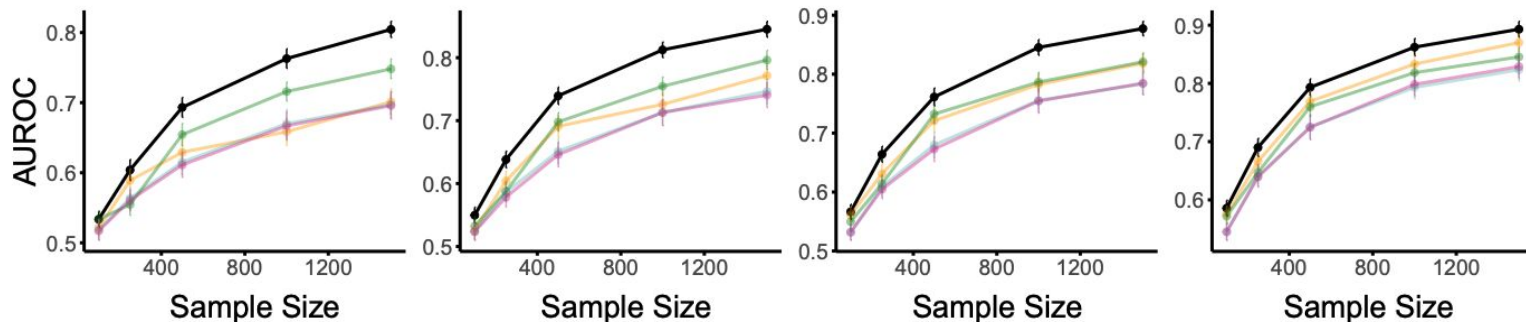
# Regression simulation results

Increasing Proportion of Variance Explained (PVE) [i.e., signal]  $\longrightarrow$

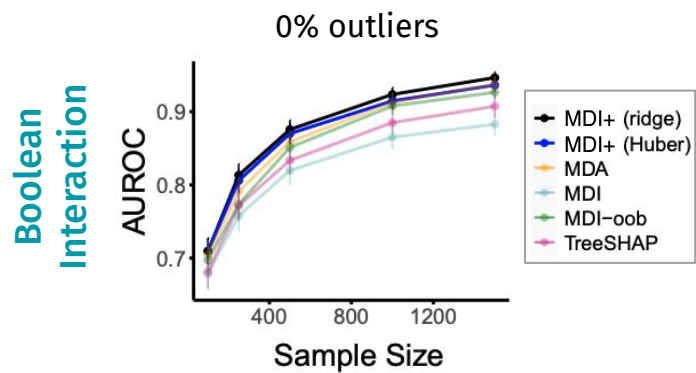
Linear



Polynomial Interaction

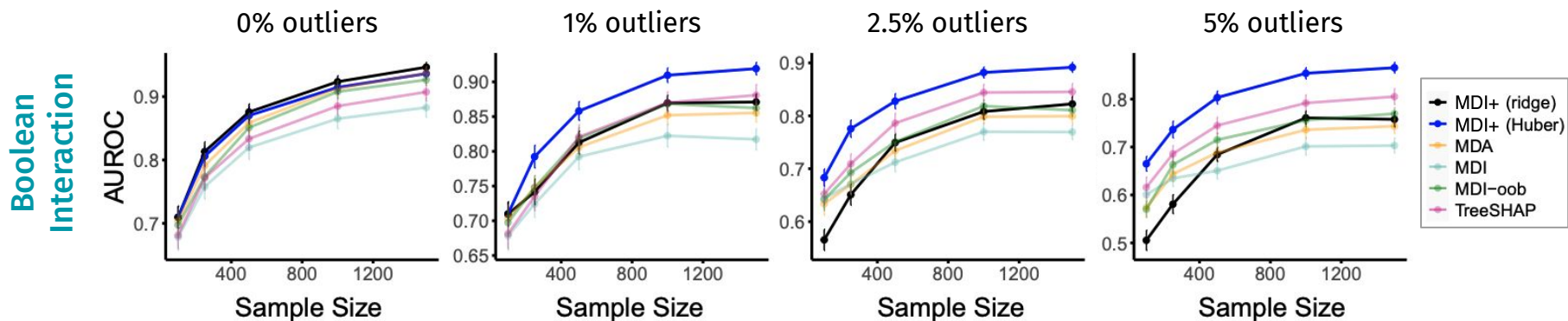


# In the presence of outliers



# In the presence of outliers

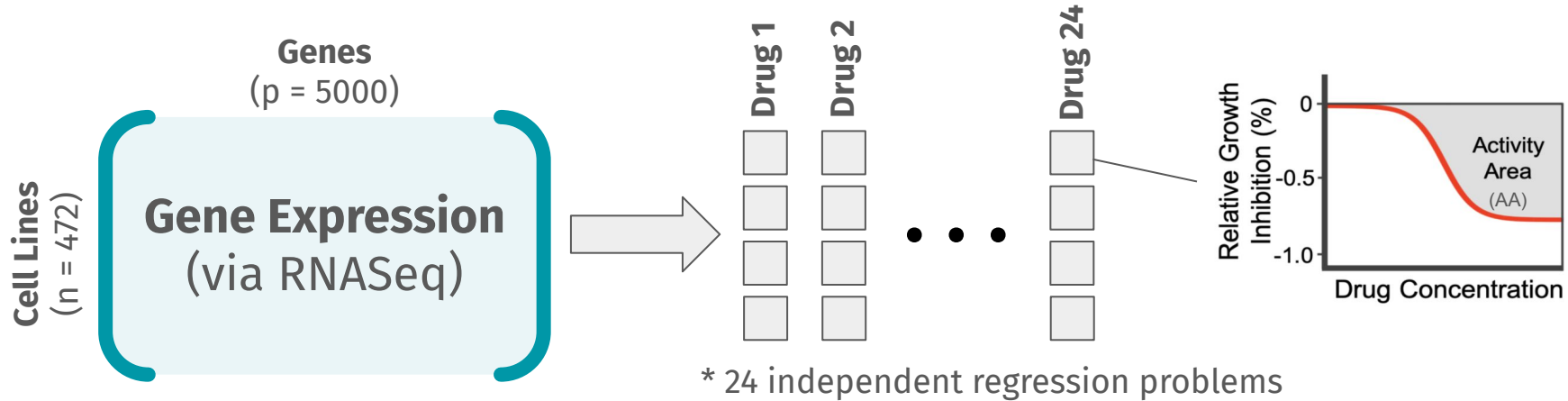
## Tailoring MDI+ to the problem setting improves feature ranking accuracy



# Real Data Case Studies

## Predicting cancer drug responses (regression)

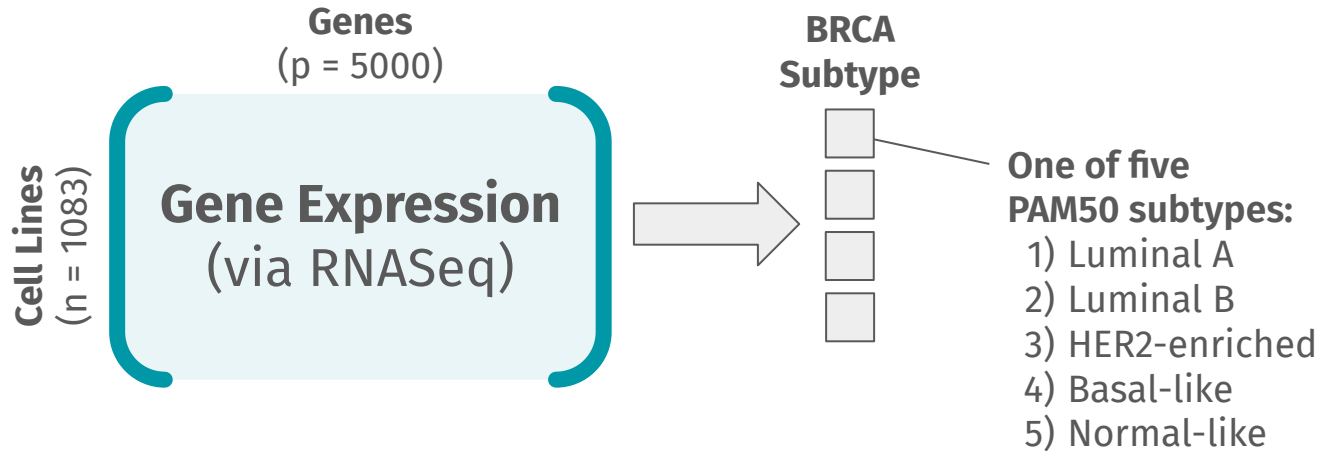
Dataset: Cancer Cell Line Encyclopedia [Barretina et al. (2012)]



# Real Data Case Studies

## Predicting breast cancer subtypes (classification)

Dataset: The Cancer Genome Atlas (TCGA) [Parker et al. (2009)]



# Case Study Objectives

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If we apply the feature importance method to 32 different RF fits (all trained on the same real  $X$  and  $y$ ), are the feature rankings **accurate** and **stable**?

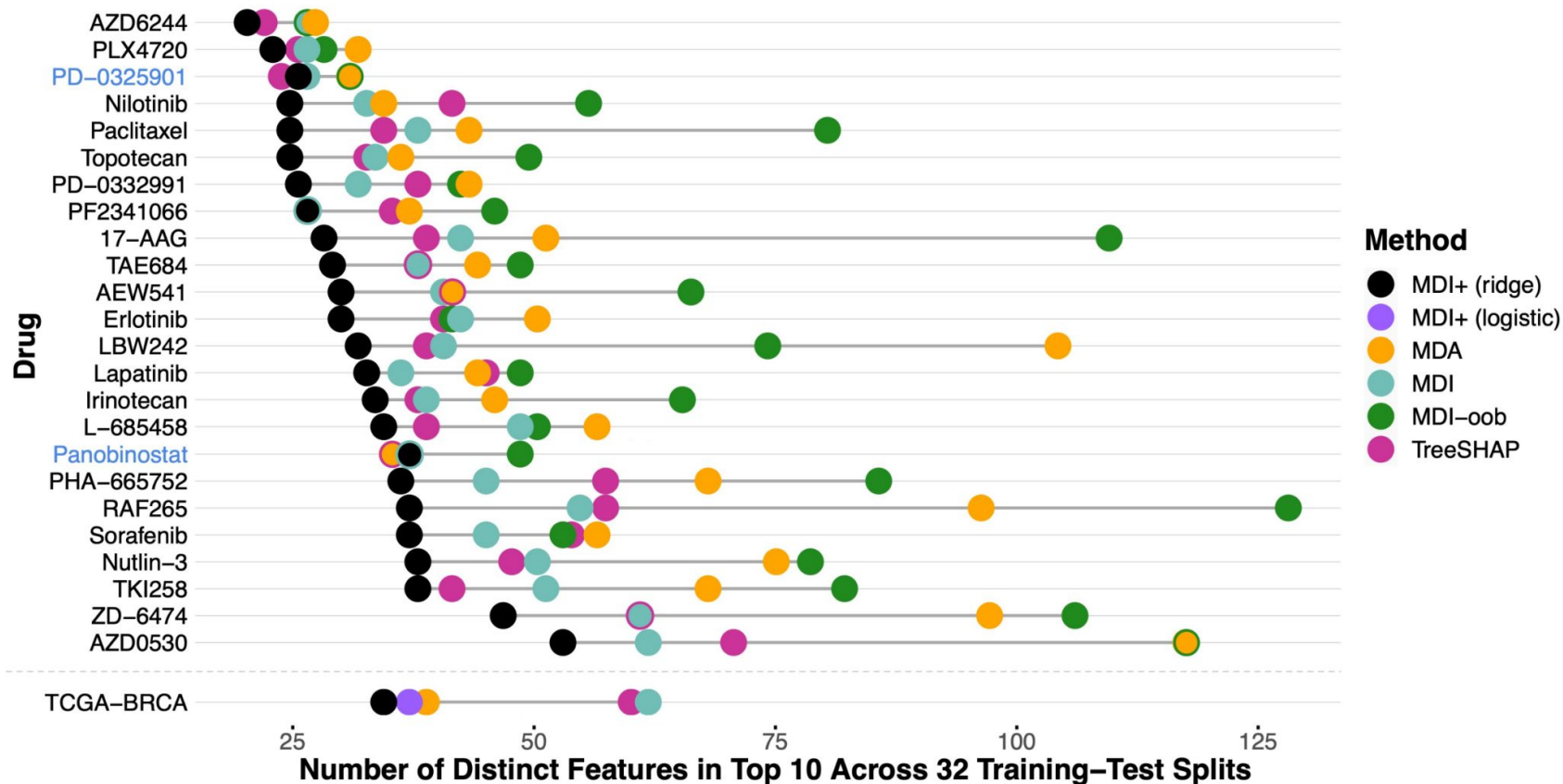
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**Accuracy:** MDI+ identified all top gene expression predictors from the original CCLE paper [Barretina et al. (2012)]

- + NQO1 gene for 17-AAG; EGFR gene for Erlotinib; ERBB2 gene for Lapatinib; MDM2 gene for Nutlin-3; MET, HGF genes for PF2341066

**Stability:** The feature rankings from MDI+ are more stable across the different RF fits, compared to competing methods (MDI, MDI-oob, MDA, TreeSHAP)

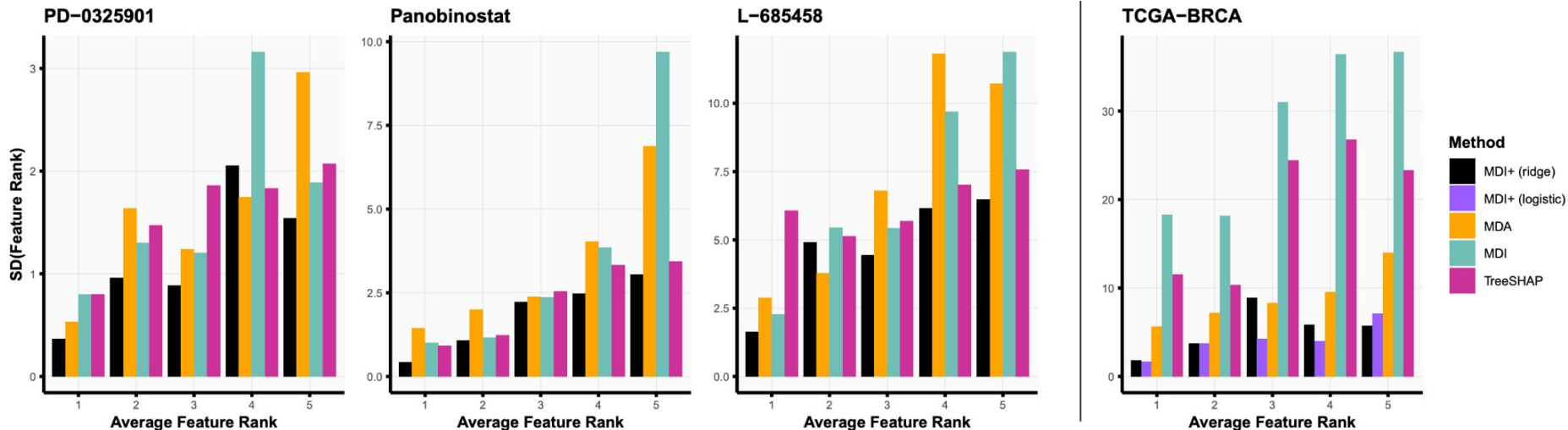
# MDI+ is more stable w.r.t. randomness in RF fits



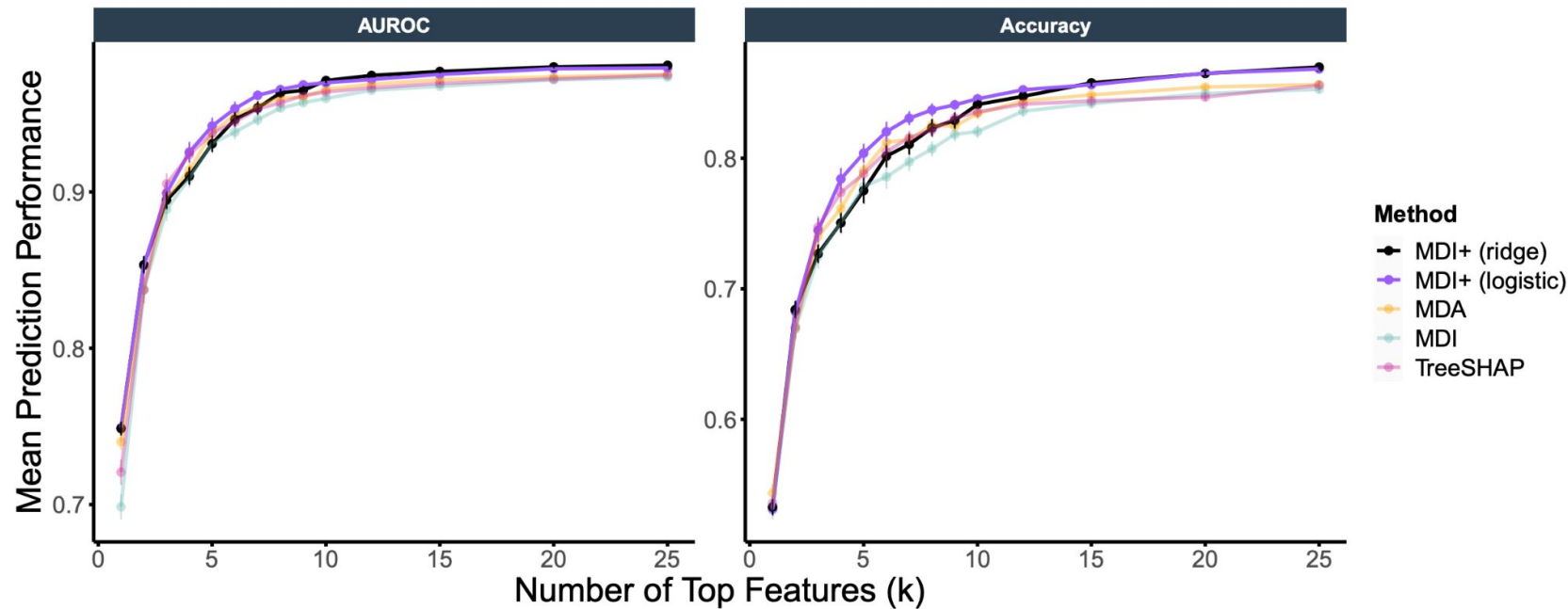


# MDI+ is more stable w.r.t. randomness in RF fits

A closer look at the top 5 features shows their ranking distribution is tighter (i.e., more stable) for MDI+ relative to competitors.



# Top MDI+ features are predictive of breast cancer subtypes



# Summary and Discussion

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- + **RF+ and MDI+:** provide a flexible random forest-based framework that
  - Overcomes many of the inductive biases of RF/decision trees and limitations of MDI
  - Allows the analyst to tailor the feature importance computation to the data/problem structure
- + **Key building block:** rethinking RF/MDI as a linear model
- + **Connection between decision trees and linear regression** opens the door to many interesting future directions
  - A new class of prediction algorithms that leverage the tree basis/stump features
  - Possibility to build upon familiar linear regression tools (e.g., for inference)

# Thank you!

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Website: [tiffanymtang.github.io](https://tiffanymtang.github.io)

Code in `imodels` python package: <https://github.com/csinva/imodels>

Preprint (RF+/MDI+): <https://arxiv.org/abs/2307.01932>

Preprint (NeRF+): in progress

## Collaborators:



Abhineet  
Agarwal



Ana  
Kenney



Yan Shuo  
Tan



Bin  
Yu



Ji  
Zhu



Elizaveta (Liza)  
Levina

# Appendix

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# Correlation bias simulation setup

## $X$ generated with block covariance structure

$X \sim N(0, \Sigma)$  with  $n = 250$ ,  $p = 100$

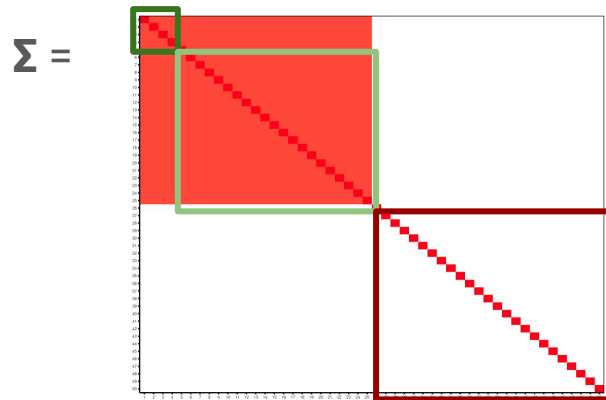
5 “Correlated Signal” features (Sig)

45 “Correlated Non-signal” features (C-NSig)

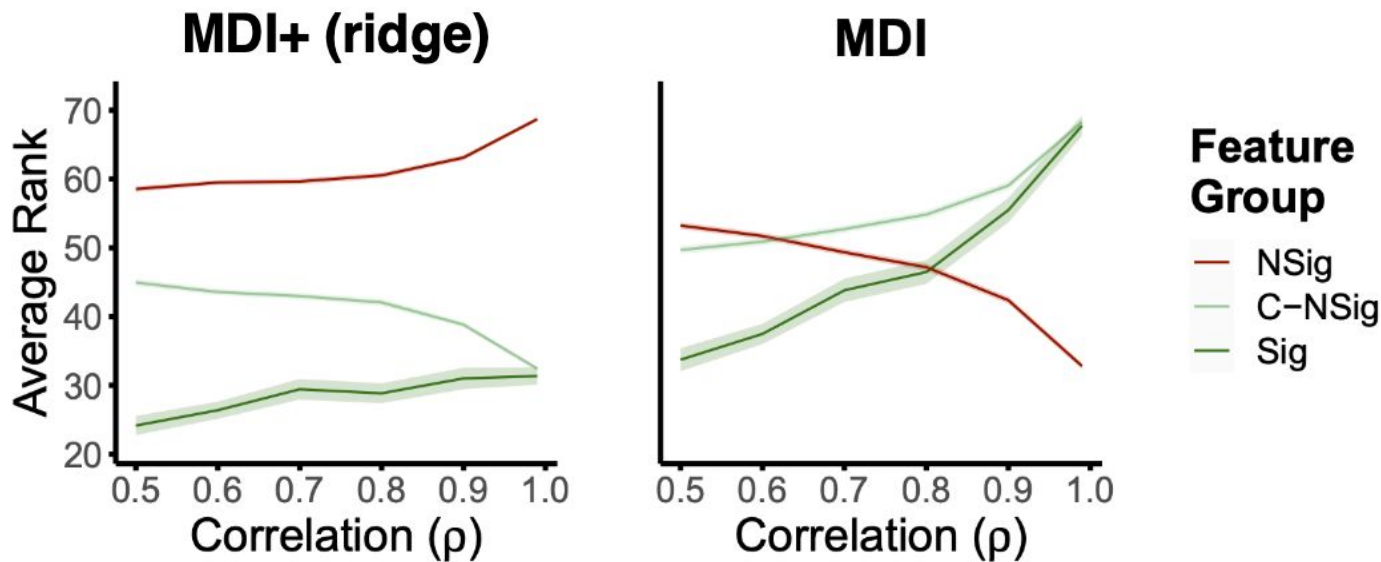
50 “Uncorrelated Non-signal” features (NSig)

## $y$ generated from sparse linear function

$$y = x_1 + x_2 + x_3 + x_4 + x_5 + \varepsilon, \quad \varepsilon \sim N(0, \sigma^2)$$



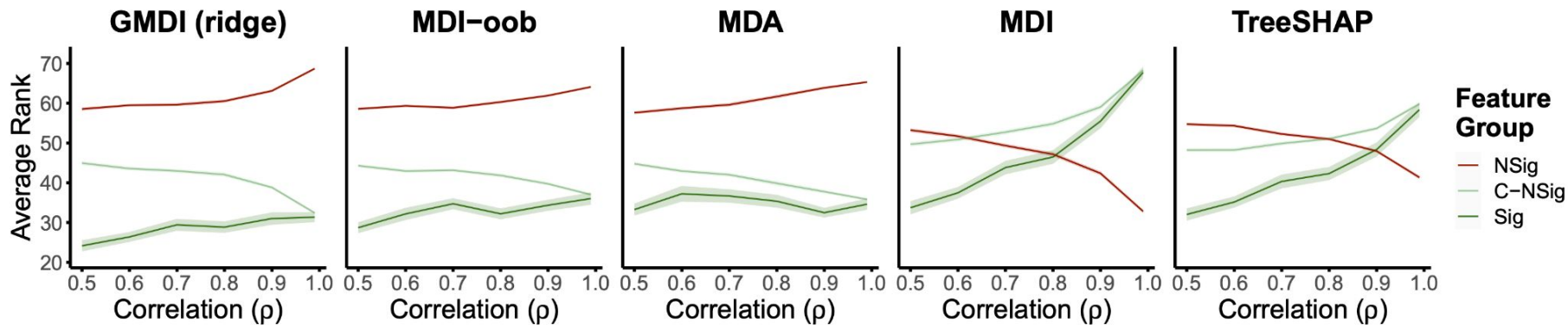
# GMDI mitigates **correlated** feature bias



MDI+ overcomes bias by using **out-of-sample prediction**

MDI ranks non-signal features as more important than signal features

# GMDI mitigates **correlated** feature bias



MDI+, MDI-oob, and MDA overcome bias by using **out-of-sample prediction**

MDI and TreeSHAP rank non-signal features as more important than signal features